

A Fault Tolerance Bisimulation Proof for Consensus

Adrian Francalanza¹ Matthew Hennessy²

¹Department of Computing
Imperial College

²Department of Informatics
University of Sussex

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Outline

- 1 Motivation
- 2 Methodology
- 3 Conclusions

Outline

1 Motivation

2 Methodology

3 Conclusions

Distributed Systems: Consensus

Consensus Setting

- n autonomous participants who may independently fail
- hold a value $v \in V$.
- must decide on a value $v' \in V$.

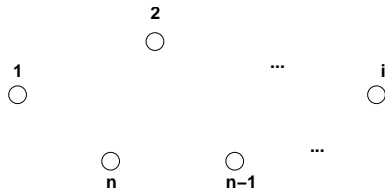
Defining Correctness of Consensus

Termination: All non-failing participants must eventually decide.

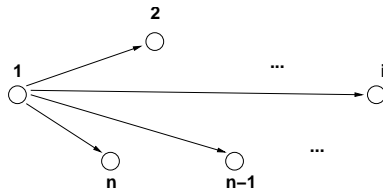
Agreement: No two participants decide on different values.

Validity: If all participants are given the same value $v \in V$ as input, then v is the only possible decision value.

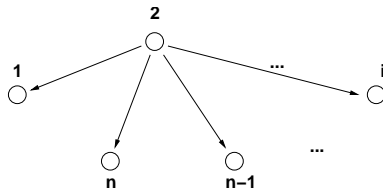
Rotating Coordinator Algorithm



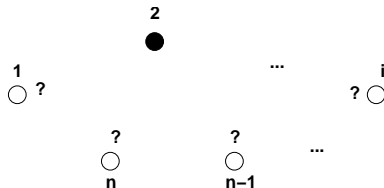
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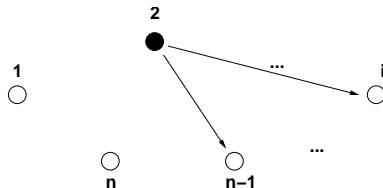
Rotating Coordinator Algorithm



Problems caused by Failure

Decision Blocking: a participant waiting forever for a value to be broadcast from a crashed co-ordinator

Rotating Coordinator Algorithm



Problems caused by Failure

Decision Blocking: a participant waiting forever for a value to be broadcast from a crashed co-ordinator

Corrupted Broadcast: a co-ordinator broadcasts its values to a *subset* of the participants before crashing.

Distributed Systems: Consensus with Perfect Failure Detection

Rotating Coordinator Algorithm for Participant i

```
part[1..n]; \\ array of n participants
x_i := input; \\ initialise
for r := 1 to n do {
  if (r = i) then broadcast(x_i);
  if alive(part[r]) then x_i := input(part[r]);
}
output x_i; \\ decide
```

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The Process Calculi Way

Language: Parallel composition, atomic actions, action hiding, reduction semantics

Bisimulation: Its and \approx characterises behavioural equivalence

The Process Calculi Way

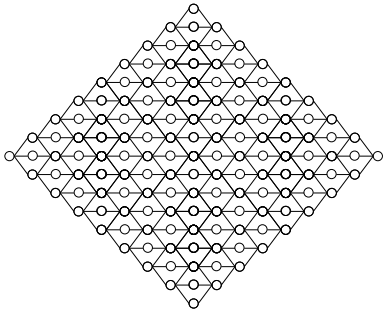
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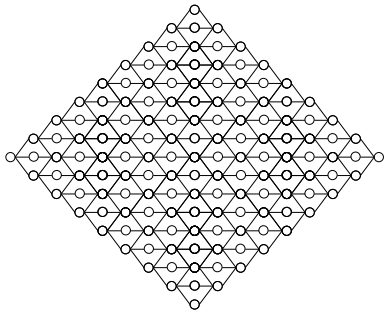
Theorem

$$P | P | \dots | P \approx SPEC$$

The Process Calculi Way (2)



The Process Calculi Way (2)



- complex to understand
- hard to digest
- not intuitive

The Process Calculi Way ... with Failures!

Language: Parallel composition, atomic actions, action hiding, reduction semantics **with failures**.

Bisimulation: Its and \approx characterises behavioural equivalence

Theorem

$$I_1[P] \mid \dots \mid I_n[P] \approx \text{SPEC_FAIL}$$

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$$\frac{}{(\Gamma, n + 1) \triangleright M \xrightarrow{\tau} (\Gamma - l, n) \triangleright M} \quad \Gamma \vdash l : \text{alive}$$

Bisimulation: Its and \approx characterises behavioural equivalence

Theorem

$$\Gamma, n - 1 \triangleright l_1[P] \mid \dots \mid l_n[P] \approx \Gamma, n - 1 \triangleright \text{SPEC_FAIL}$$

The Process Calculi Way ... with Failures!

Expressing Participant i in our process calculus

(Participant)

$$P_{i,r}^x \stackrel{\text{def}}{=} R_{i,r}^x \mid B_{i,r}^x \quad x \in \{true, false\}, r \leq n$$

$$P_{i,n+1}^x \stackrel{\text{def}}{=} \overline{dec}_i^x \quad x \in \{true, false\}$$

(Receive)

$$R_{i,r}^x \stackrel{\text{def}}{=} true_{i,r}.P_{i,r+1}^{true} + false_{i,r}.P_{i,r+1}^{false} + \text{susp } l_r.P_{i,r+1}^x$$

(Broadcast)

$$B_{i,i}^x \stackrel{\text{def}}{=} \prod_{j=1}^n \overline{x}_{j,r} \quad x \in \{true, false\}$$

$$B_{i,r}^x \stackrel{\text{def}}{=} \mathbf{0} \quad x \in \{true, false\}, r \neq i$$

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The Process Calculi Way ... with Failures!

Composing n Participants to solve Consensus

$$C \stackrel{\text{def}}{=} \left(\nu_{i,r=1}^n \begin{array}{l} \text{true}_{i,r}, \\ \text{false}_{i,r} \end{array} \right) \prod_{i=1}^n l_i \left[\left[\begin{array}{l} \text{prop}_i^{\text{true}} . P_{i,1}^{\text{true}} \\ + \text{prop}_i^{\text{false}} . P_{i,1}^{\text{false}} \end{array} \right] \right]$$

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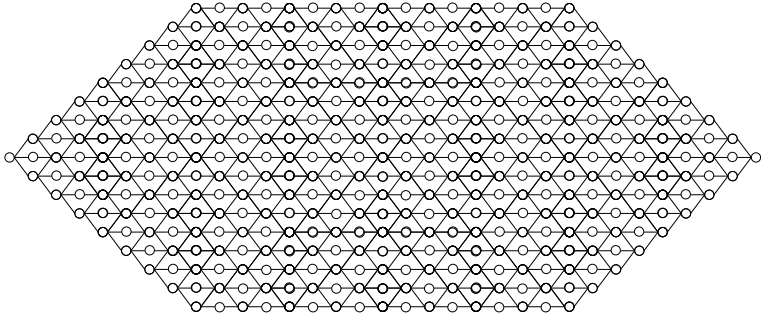
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Specification in the presence of Failure

VERY COMPLEX!

Bisimulation with Failure



An even bigger, more complex bisimulation!

Outline

1 Motivation

2 Methodology

3 Conclusions

Methodology (1): Testing Harnesses

Language: Parallel composition, atomic actions, action hiding, reduction semantics w. failures, **immortal location** \star .

Bisimulation: Its and \approx characterises behavioural equivalence **w.r.t** **immortal observers**

Theorem

$$\Gamma, n - 1 \triangleright (\nu \tilde{m})(\star[Q] \mid l_1[P] \mid \dots \mid l_n[P]) \approx \Gamma, 0 \triangleright \star[SPEC]$$

Methodology (1): Testing Harnesses

Language: ...

Bisimulation: ...

Theorem

$$\Gamma, n - 1 \triangleright (\nu \tilde{m})(\star[Q] \mid l_1[P] \mid \dots \mid l_n[P]) \approx \Gamma, 0 \triangleright \star[SPEC]$$

Advantages

- 1 Simplifies specification formulation
- 2 Permits separate tests for correctness criteria

Methodology (1): Testing Harnesses

Harnesses For Consensus

(Initialisation)

$$I^x \stackrel{\text{def}}{=} \text{start. } \prod_{i=1}^n \overline{\text{prop}_i^x} \quad x \in \{\text{true}, \text{false}\}$$

$$I^{\text{gen}} \stackrel{\text{def}}{=} \text{start. } \prod_{i=1}^n (\overline{\text{prop}_i^{\text{true}}} + \overline{\text{prop}_i^{\text{false}}})$$

(Agreement)

$$A_i^x \stackrel{\text{def}}{=} \text{dec}_i^x . A_{i+1}^x + \text{susp } l_i . A_{i+1}^x \quad \begin{array}{l} x \in \{\text{true}, \text{false}\} \\ , i \leq n \end{array}$$

$$A_{n+1}^x \stackrel{\text{def}}{=} \overline{\text{ok}} \quad x \in \{\text{true}, \text{false}\}$$

$$A_i^{\text{gen}} \stackrel{\text{def}}{=} \text{dec}_i^{\text{true}} . A_{i+1}^{\text{true}} + \text{dec}_i^{\text{false}} . A_{i+1}^{\text{false}} + \text{susp } l_i . A_{i+1}^{\text{gen}}$$

Methodology (1): Testing Harnesses

Language: ...

Bisimulation: ...

Theorem

Agreement and Termination

$$\Gamma, n - 1 \triangleright (\nu \tilde{m})(\star [I^{gen} | A_1^{gen}] | C) \approx \Gamma, 0 \triangleright \star [start.\overline{ok}]$$

Validity

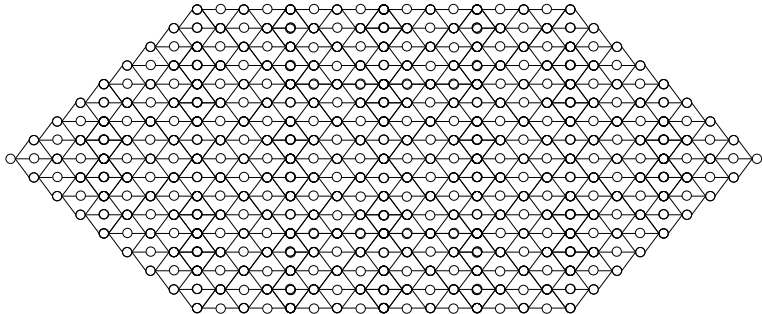
$$\Gamma, n - 1 \triangleright (\nu \tilde{m})(\star [I^{true} | A_1^{true}] | C) \approx \Gamma, 0 \triangleright \star [start.\overline{ok}]$$

$$\Gamma, n - 1 \triangleright (\nu \tilde{m})(\star [I^{false} | A_1^{false}] | C) \approx \Gamma, 0 \triangleright \star [start.\overline{ok}]$$

$$\tilde{m} = \prod_{i=1}^n prop_i^{true}, prop_i^{false}, dec_i^{true}, dec_i^{false}$$

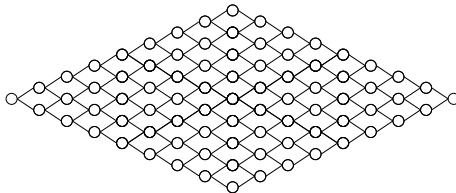


Methodology (1): ... on the bisimulation front

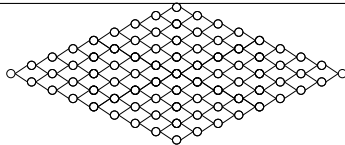


Where we left off... (big, complex bisimulation!)

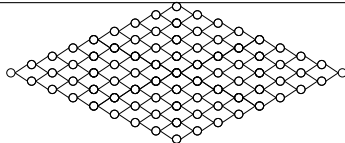
Methodology (1): ... on the bisimulation front



Agreement



Validity



Methodology (2): Fault Tolerance

Language: ...

Bisimulation: ...

Theorem

$$\Gamma, n - 1 \triangleright (\nu \tilde{m})(\star \llbracket I|A \rrbracket \mid C) \approx \Gamma, 0 \triangleright \star \llbracket \text{start.}\overline{ok} \rrbracket$$

Methodology (2): Fault Tolerance

Language: ...

Bisimulation: ...

Theorem

$$\Gamma, n - 1 \triangleright (\nu \tilde{m})(\star \llbracket I \mid A \rrbracket \mid \underbrace{C}_{\text{Induce failure}}) \approx \Gamma, 0 \triangleright \star \llbracket \text{start.ok} \rrbracket$$

Methodology (2): Fault Tolerance

Language: ...

Bisimulation: ...

Theorem

$$\begin{array}{ccc}
 \text{Preserve} & & \text{Preserve} \\
 \text{observable} & & \text{observable} \\
 \text{behaviour} & & \text{behaviour} \\
 \Gamma, n-1 \triangleright (\nu \tilde{m}) \quad \overbrace{\star[[I|A]]} & | \quad \underbrace{C}_{\text{Induce failure}} & \approx \Gamma, 0 \triangleright \overbrace{\star[[\text{start}.\overline{\text{ok}}]]}
 \end{array}$$

Methodology (2): Fault Tolerance

Language: ...

Bisimulation: ...

Theorem

$$\Gamma, n - 1 \triangleright (\nu \tilde{m})(\star \llbracket I|A \rrbracket \mid C) \approx \Gamma, 0 \triangleright \star \llbracket \text{start.ok} \rrbracket$$

Methodology (2): Fault Tolerance

Language: ...

Bisimulation: ...

Theorem

Basic Correctness

$$\Gamma, 0 \triangleright (\nu \tilde{m})(\star \llbracket I/A \rrbracket \mid C) \approx \Gamma, 0 \triangleright \star \llbracket \text{start.}\overline{ok} \rrbracket$$

Methodology (2): Fault Tolerance

Language: ...

Bisimulation: ...

Theorem

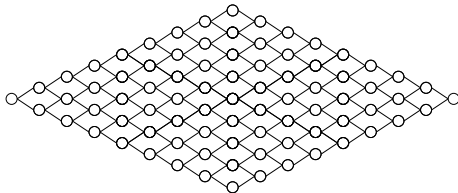
Basic Correctness

$$\Gamma, 0 \triangleright (\nu \tilde{m})(\star \llbracket I|A \rrbracket \mid C) \approx \Gamma, 0 \triangleright \star \llbracket \text{start.}\overline{ok} \rrbracket$$

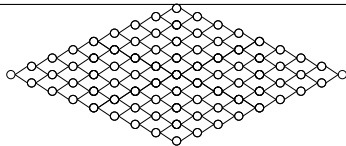
Correctness Preservation

$$\Gamma, n-1 \triangleright (\nu \tilde{m})(\star \llbracket I|A \rrbracket \mid C) \approx \Gamma, 0 \triangleright (\nu \tilde{m})(\star \llbracket I|A \rrbracket \mid C)$$

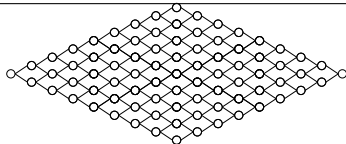
Methodology (2): ... on the bisimulation front



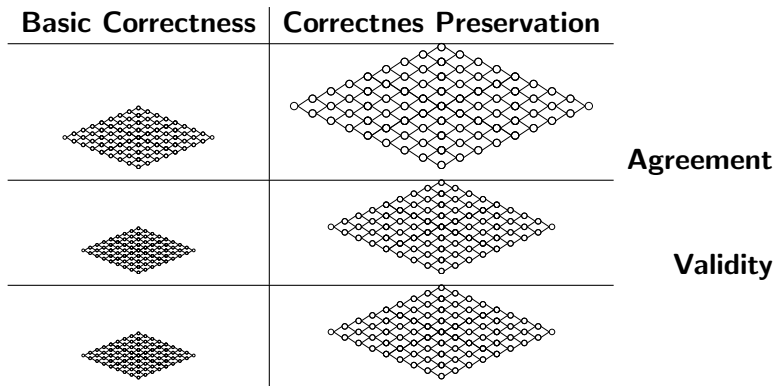
Agreement



Validity



Methodology (2): ... on the bisimulation front



Methodology (2): Advantages

- 1 **Natural** way how to analyse algorithms in the presence of failure.
- 2 **Stages are Independent:**
 - Test them in parallel
 - Simpler (failure-free) stage can be used as a vetting stage
- 3 **Refined Up-to Techniques:** we have different confluences and structural equivalences under different failure settings.

Methodology (3): Up-to Techniques

Confluence Properties

$$\langle \Gamma, n \rangle \triangleright N \xrightarrow{\tau} \beta \langle \Gamma, n \rangle \triangleright M$$

Methodology (3): Up-to Techniques

Confluence Properties

$$\begin{array}{ccc} \langle \Gamma, n \rangle \triangleright N & \xrightarrow{\tau} & \langle \Gamma, n \rangle \triangleright M \\ \mu \downarrow & & \\ \langle \Gamma', n' \rangle \triangleright N' & & \end{array}$$

Methodology (3): Up-to Techniques

Confluence Properties

$$\begin{array}{ccc}
 \langle \Gamma, n \rangle \triangleright N \xrightarrow{\tau} \langle \Gamma, n \rangle \triangleright M & & \\
 \mu \downarrow & & \mu \downarrow \\
 \langle \Gamma', n' \rangle \triangleright N' \xrightarrow{\tau} \langle \Gamma', n' \rangle \triangleright M' & & \\
 \beta & & \beta
 \end{array}$$

Methodology (3): Up-to Techniques

Structural Equivalence Properties

$$\langle \Gamma, n \rangle \triangleright N \quad \equiv \quad \langle \Gamma, n \rangle \triangleright M$$

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Methodology (3): Up-to Techniques

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Methodology (3): Up-to Techniques

Confluence in a Failure-free Setting

$$\Gamma, 0 \triangleright (\nu a) (l[\bar{a}] \mid k[a.P])$$

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Confluence in a Failure-free Setting

$$\Gamma, 0 \triangleright (\nu a) (l[\bar{a}] \mid k[a.P]) \quad \xrightarrow{\tau}_{\beta} \quad \Gamma, 0 \triangleright (\nu a) (k[P])$$

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Confluence in a Failure Setting

$$\Gamma, n \triangleright (\nu a) (l[\bar{a}] \mid k[a.P + \text{susp } l.P])$$

Methodology (3): Up-to Techniques

Confluence in a Failure-free Setting

$$\Gamma, 0 \triangleright (\nu a) (l[\bar{a}] \mid k[a.P]) \quad \xrightarrow{\tau}_{\beta} \quad \Gamma, 0 \triangleright (\nu a) (k[P])$$

Confluence in a Failure Setting

$$\Gamma, n \triangleright (\nu a) (l[\bar{a}] \mid k[a.P + \text{susp } l.P]) \quad \xrightarrow{\tau}_{\beta} \quad \Gamma, n \triangleright (\nu a) (k[P])$$

Methodology (3): Up-to Techniques

Structural Equivalence in a Failure-free Setting

$$\Gamma, 0 \triangleright I[P + \text{susp } k.Q] \equiv \Gamma, 0 \triangleright I[P] \quad \Gamma \vdash k : \mathbf{alive}$$

Methodology (3): Up-to Techniques

Confluence Within Consensus

$$\Gamma, n \triangleright \left(\nu \begin{array}{l} true_{i,j}, \\ false_{i,j} \end{array} \right) (I_j \llbracket true_{i,j} \rrbracket \mid I_i \llbracket true_{i,j}.P + false_{i,j}.Q + susp I.R \rrbracket)$$

Methodology (3): Up-to Techniques

Confluence Within Consensus

$$\Gamma, n \triangleright \left(\nu \begin{array}{l} true_{i,j}, \\ false_{i,j} \end{array} \right) \left(\underbrace{l_j \llbracket true_{i,j} \rrbracket}_{\text{coordinator}} \mid \underbrace{l_i \llbracket true_{i,j}.P + false_{i,j}.Q + \text{susp } l_j.R \rrbracket}_{\text{participant}} \right) \text{ at round } j$$

Methodology (3): Up-to Techniques

Confluence Within Consensus

3 Cases

$$\Gamma, n \triangleright \left(\nu \begin{array}{l} true_{i,j}, \\ false_{i,j} \end{array} \right) (l_j \llbracket \overline{true}_{i,j} \rrbracket \mid l_i \llbracket true_{i,j}.P + false_{i,j}.Q + \text{susp } l_j.R \rrbracket)$$

Methodology (3): Up-to Techniques

Confluence Within Consensus

Failure Free

$$\Gamma, 0 \triangleright \left(\nu \begin{array}{l} true_{i,j}, \\ false_{i,j} \end{array} \right) (l_j \llbracket true_{i,j} \rrbracket \mid l_i \llbracket true_{i,j}.P + false_{i,j}.Q + susp\ l_j.R \rrbracket)$$

Methodology (3): Up-to Techniques

Confluence Within Consensus

Failure Free

$$\begin{aligned} \Gamma, 0 \triangleright & \left(\nu \begin{array}{l} true_{i,j}, \\ false_{i,j} \end{array} \right) (l_j[\overline{true}_{i,j}] \mid l_i[true_{i,j}.P + false_{i,j}.Q + \text{ susp } l_j.R]) \\ \equiv & (\nu true_{i,j}, false_{i,j}) (l_j[\overline{true}_{i,j}] \mid l_i[true_{i,j}.P + false_{i,j}.Q]) \end{aligned}$$

Methodology (3): Up-to Techniques

Confluence Within Consensus

Failure Free

$$\begin{aligned}
 \Gamma, 0 \triangleright & \left(\nu \begin{array}{l} true_{i,j}, \\ false_{i,j} \end{array} \right) (l_j \llbracket true_{i,j} \rrbracket \mid l_i \llbracket true_{i,j}.P + false_{i,j}.Q + \text{susp } l_j.R \rrbracket) \\
 \equiv & (\nu true_{i,j}, false_{i,j}) (l_j \llbracket true_{i,j} \rrbracket \mid l_i \llbracket true_{i,j}.P + false_{i,j}.Q \rrbracket) \\
 \equiv & (\nu true_{i,j}, false_{i,j}) (l_j \llbracket true_{i,j} \rrbracket \mid l_i \llbracket true_{i,j}.P \rrbracket)
 \end{aligned}$$

Methodology (3): Up-to Techniques

Confluence Within Consensus

Failure Free

$$\begin{aligned}
 \Gamma, 0 &\triangleright \left(\nu \begin{array}{l} true_{i,j}, \\ false_{i,j} \end{array} \right) (l_j[\overline{true}_{i,j}] \mid l_i[true_{i,j}.P + false_{i,j}.Q + \text{susp } l_j.R]) \\
 &\equiv (\nu true_{i,j}, false_{i,j}) (l_j[\overline{true}_{i,j}] \mid l_i[true_{i,j}.P + false_{i,j}.Q]) \\
 &\equiv (\nu true_{i,j}, false_{i,j}) (l_j[\overline{true}_{i,j}] \mid l_i[true_{i,j}.P]) \\
 &\stackrel{\tau}{\rightarrow}_{\beta} (\nu true_{i,j}, false_{i,j}) (l_i[P])
 \end{aligned}$$

Methodology (3): Up-to Techniques

Confluence Within Consensus

Broadcast same as estimate

$$\Gamma, n \triangleright \left(\nu \begin{array}{l} true_{i,j}, \\ false_{i,j} \end{array} \right) (l_j \llbracket \overline{true}_{i,j} \rrbracket \mid l_i \llbracket true_{i,j}.P + false_{i,j}.Q + \text{susp } l_j.P \rrbracket)$$

Methodology (3): Up-to Techniques

Confluence Within Consensus

Broadcast same as estimate

$$\begin{aligned} \Gamma, n \triangleright \left(\nu \begin{array}{l} \text{true}_{i,j}, \\ \text{false}_{i,j} \end{array} \right) (l_j \llbracket \overline{\text{true}}_{i,j} \rrbracket \mid l_i \llbracket \text{true}_{i,j}.P + \text{false}_{i,j}.Q + \text{susp } l_j.P \rrbracket) \\ \equiv (\nu \text{true}_{i,j}, \text{false}_{i,j}) (l_j \llbracket \overline{\text{true}}_{i,j} \rrbracket \mid l_i \llbracket \text{true}_{i,j}.P + \text{susp } l_j.P \rrbracket) \end{aligned}$$

Methodology (3): Up-to Techniques

Confluence Within Consensus

Broadcast same as estimate

$$\begin{aligned}
 \Gamma, n \triangleright & \left(\nu \begin{array}{l} \text{true}_{i,j}, \\ \text{false}_{i,j} \end{array} \right) (l_j[\overline{\text{true}}_{i,j}] \mid l_i[\text{true}_{i,j}.P + \text{false}_{i,j}.Q + \text{susp } l_j.P]) \\
 \equiv & (\nu \text{true}_{i,j}, \text{false}_{i,j}) (l_j[\overline{\text{true}}_{i,j}] \mid l_i[\text{true}_{i,j}.P + \text{susp } l_j.P]) \\
 \xrightarrow{\tau} &_{\beta} (\nu \text{true}_{i,j}, \text{false}_{i,j}) (l_i[P])
 \end{aligned}$$

Methodology (3): Up-to Techniques

Confluence Within Consensus

Broadcast different from estimate

$$\Gamma, n \triangleright \left(\nu \begin{array}{l} \text{true}_{i,j}, \\ \text{false}_{i,j} \end{array} \right) (l_j \llbracket \overline{\text{true}}_{i,j} \rrbracket \mid l_i \llbracket \text{true}_{i,j}.P + \text{false}_{i,j}.Q + \text{susp } l_j.R \rrbracket)$$

Methodology (3): Up-to Techniques

Confluence Within Consensus

Broadcast different from estimate

$$\begin{aligned} \Gamma, n \triangleright \left(\nu \begin{array}{l} \text{true}_{i,j}, \\ \text{false}_{i,j} \end{array} \right) & (l_j \llbracket \text{true}_{i,j} \rrbracket \mid l_i \llbracket \text{true}_{i,j}.P + \text{false}_{i,j}.Q + \text{susp } l_j.R \rrbracket) \\ \equiv & (\nu \text{true}_{i,j}, \text{false}_{i,j}) (l_j \llbracket \text{true}_{i,j} \rrbracket \mid l_i \llbracket \text{true}_{i,j}.P + \text{susp } l_j.Q \rrbracket) \end{aligned}$$

Methodology (3): Up-to Techniques

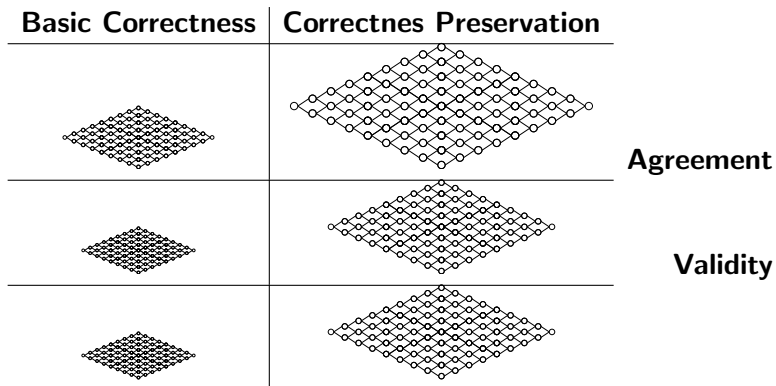
Why is it worthwhile...?

- techniques for attaining fault tolerance are bounded and reused in many algorithms.
- Fault tolerance is attained through **replication!**

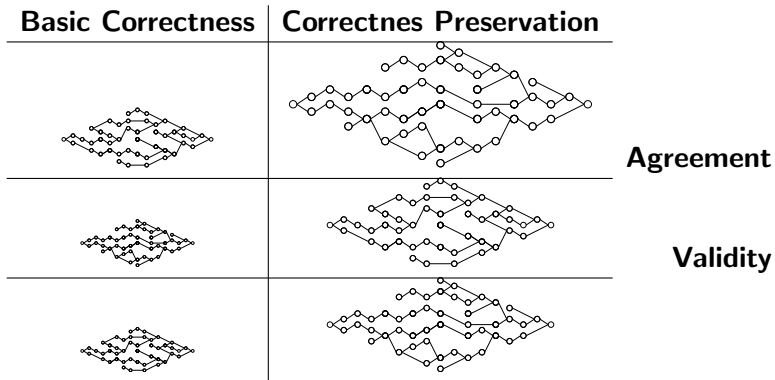
Space replication: $P|P|\dots|P$

Time replication: $P.P\dots P$

Methodology (3): ... on the bisimulation front



Methodology (3): ... on the bisimulation front



Outline

1 Motivation

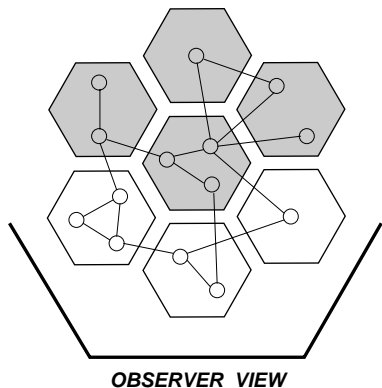
2 Methodology

3 Conclusions

Methodology in 3 acts

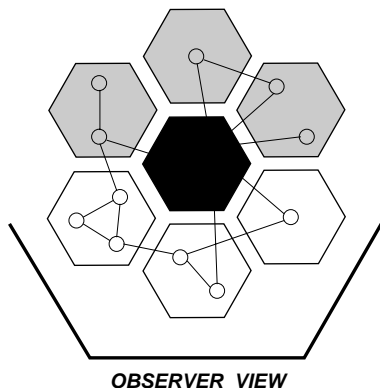
- 1 Testing Harnesses:** Limiting observations to non-failing locations.
- 2 Fault Tolerance:** Splitting analysis into basic correctness and correctness preservation phases.
- 3 Refined Up-to Techniques:** for both failure-free and failure phases.

Fault Tolerance (...in a nut shell)



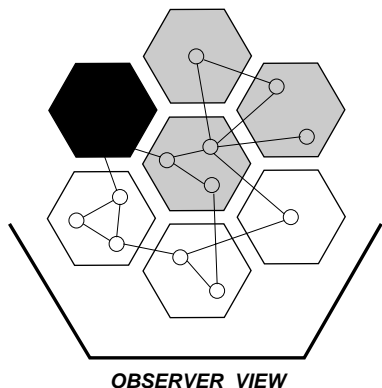
Restrict observation to
immortal locations

Fault Tolerance (...in a nut shell)



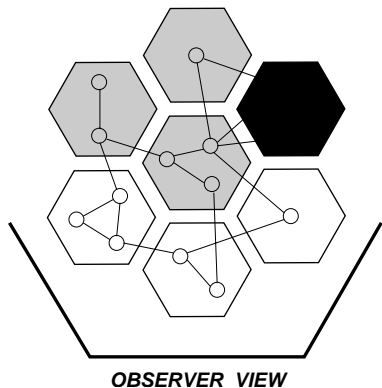
Preserves observation up to 1 failure

Fault Tolerance (...in a nut shell)



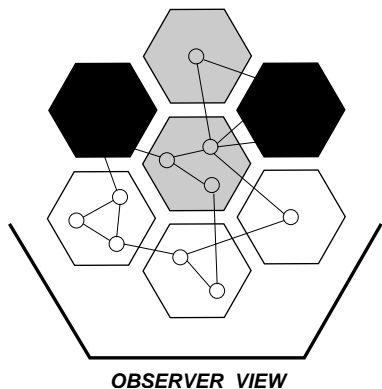
Preserves observation up to 1 failure

Fault Tolerance (...in a nut shell)



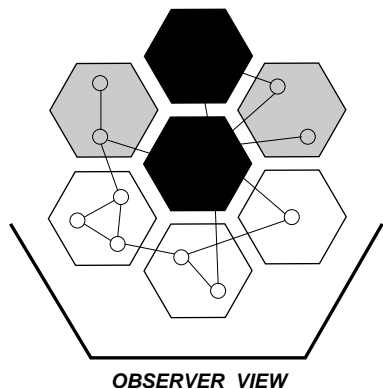
Preserves observation up to 1 failure

Fault Tolerance (...in a nut shell)



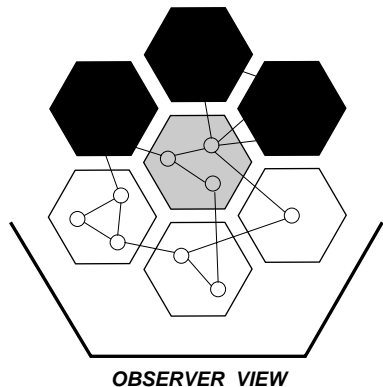
Preserves observation up to 2 failures

Fault Tolerance (...in a nut shell)



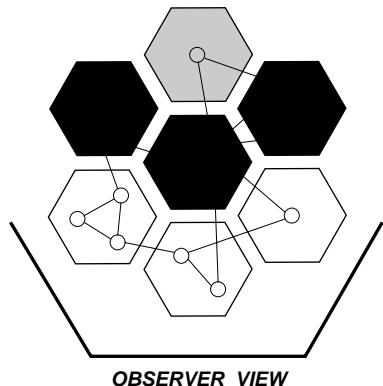
Preserves observation up to 2 failures

Fault Tolerance (...in a nut shell)



Preserves observation up to
3 failures

Fault Tolerance (...in a nut shell)



Preserves observation up to
3 failures